

The π -Calculus for SoS: Novel π -Calculus for the Formal Modeling of Software-intensive Systems-of-Systems

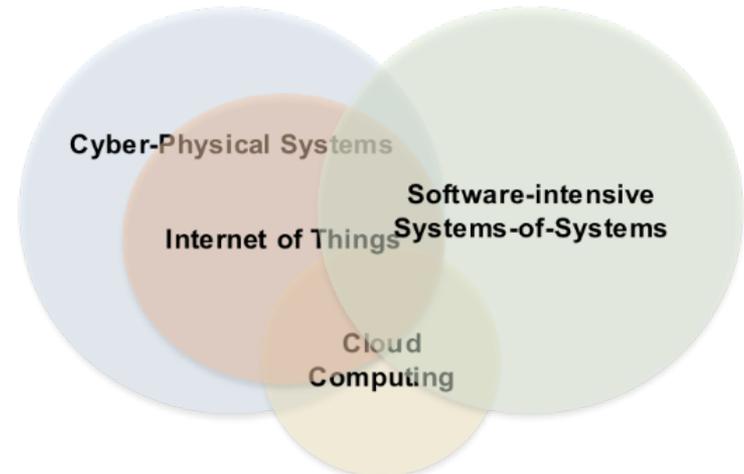
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Outline

- **Introduction: Motivation to conceive the π -Calculus for SoS**
 - Need of formal description techniques to model SoS architectures
 - Limitations of current formal description techniques
- **Problematics**
 - Needs for a novel process calculus for SoS
- **Formal Approach for Conceiving the π -Calculus for SoS**
 - Novel process calculus meeting SoS needs: The π -Calculus for SoS
- **Formal Definition of the π -Calculus for SoS**
 - Formal transition system defining the π -Calculus for SoS
- **Validating the Formal Operational Semantics of the π -Calculus for SoS**
- **Conclusion**

Introduction: Software-intensive System-of-Systems

- **Software-intensive Systems-of-Systems (SoS)**
 - Systems are independently developed, operated, managed, evolved and eventually retired
 - Increasingly, networks make communication and cooperation possible among these independent systems
 - These networked systems evolved to form **Systems-of-Systems**
 - Systems-of-Systems are evolutionary developed from independent systems to achieve missions not possible by a constituent system alone
 - SoS creates emergent behavior
 - Systems-of-Systems have **evolutionary architectures**



Introduction: System-of-Systems Architecture

- **Software-intensive Systems**
 - were simple and became complicated: needs engineering
 - are becoming complex as **SoS: needs architecture**
 - complexity poses the need for separation of concerns between architecture and engineering
 - **architecture: focus on reasoning about interactions of parts and their emergent properties**
- **Issues:**
 - **Do the process calculi constituting the formal foundations of ADLs for single systems provide enough expressive power for modeling SoS architectures?**
 - **Beyond the process calculi underlying single system ADLs, are there other process calculi that would be suitable for describing SoS architectures?**

Limitations of the state-of-the-art ADLs for describing SoS Architectures

- **Software Architecture Description Language (ADL)**
 - Subject of intensive research in the last 20 years
 - Proposal of several ADLs for formally describing Software Architecture (see IFIP/IEEE ICSA, ECSA, QoSA...; IEEE TSE, ACM TOSEM, JSS, FGCS, IEEE Software...)
- **ADLs for Single Systems**
 - **None of those ADLs has the expressive power to describe the Software Architecture of a Software-intensive SoS**
 - **Formal foundations of these ADLs are too limited to describe SoS Architectures**
- **A novel formal foundation is needed for representing, analyzing and evolving SoS Architectures**
 - **Need of a novel formal foundation to describe SoS Architectures**



Formal Foundations of ADLs for Single Systems: Process Calculi

- **Formal foundations** for describing the **Architecture of Single Systems** are mostly based on **Process Calculi**
 - **FSP**: the formal foundation of Darwin ADL
 - **CSP**: the formal foundation of Wright ADL
 - **π -Calculus**: the formal foundation of π -ADL
- **Process Calculi**
 - **Mathematical theory** for formally modeling concurrent communicating systems
 - provide a formalism for the description of communicating processes
 - provide algebraic laws that allow process descriptions to be manipulated and analyzed
 - enable formal reasoning about equivalences between processes
 - **The Process Calculus of reference**
 - **The π -Calculus** (ACM Turing Award for Robin Milner in 1991)

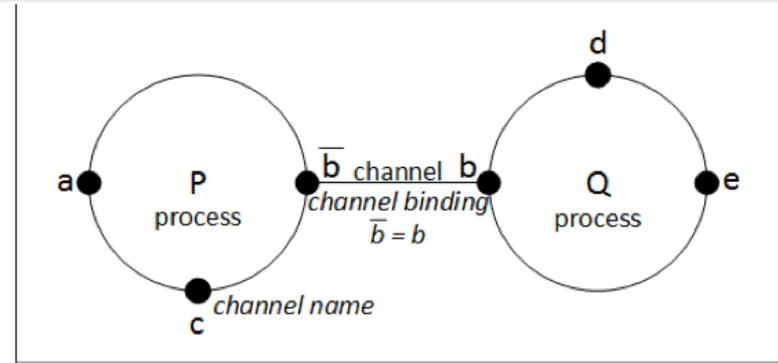
Formal Foundations of ADLs for Single Systems: The π -Calculus

■ π -Calculus

■ Basic concepts

- **Processes** (single and composite processes)
- **Channels** (interaction points) – channels support the **binding** of interaction points in concurrent processes
- **Names** (including channel names)
- **Mobility** (channels are used to send and receive names that may be channels)

- π -Calculus has shown to be a **suitable formal foundation for describing and analyzing the architecture of software-intensive single systems**
- However, π -Calculus as well as other process calculi, e.g. **FSP/CSP**, are too limited to cope with SoS architecture needs



Formal Foundations of ADLs for Single Systems: Process Calculi

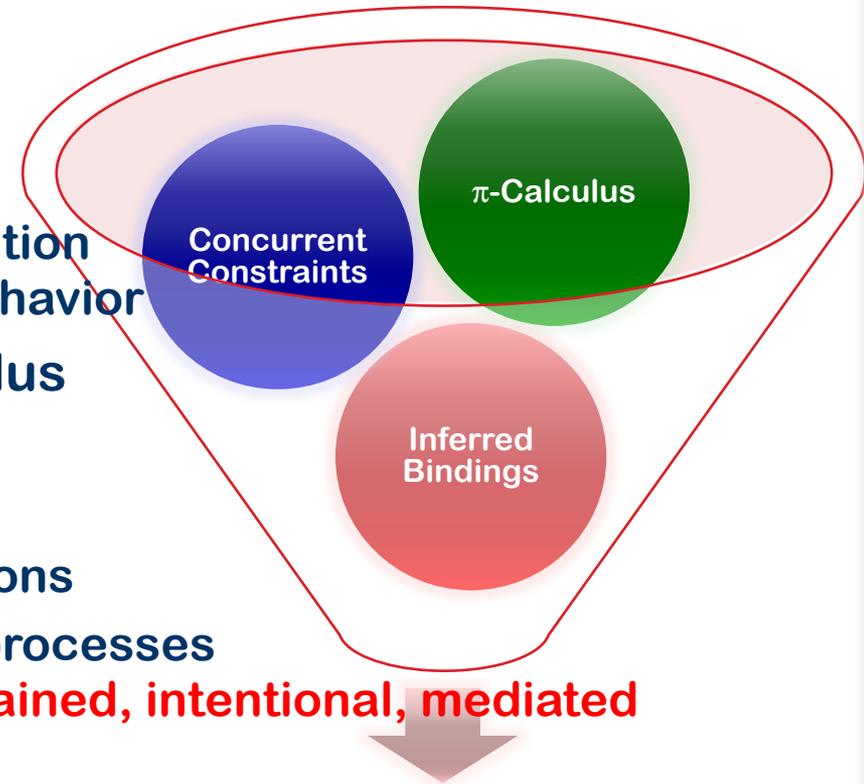
- Different process calculi were applied for formally describing the architecture of single software-intensive systems
 - Including different variants of the π -Calculus
- Bindings in all these process calculi for the architecture description of single software-intensive systems are:
 - **endogenously** decided at design-time
 - **extensionally** declared at design-time
 - **unconstrained** by local environments
 - **unmediated** between constituents
- Expressive power of these **process calculi based on design-time decisions do not cope with SoS** defining characteristics
- Research question:
 - **How to enhance the π -Calculus for formally describing SoS architectures?**

Differences of Description Needs between Single Systems and Systems-of-Systems

- None of the existing π -Calculi provides a suitable basis for formally describing and analyzing SoS architectures
- Needs related to SoS Architecture Description
 - Representing systems as **processes**
 - Representing mediators between communicating processes via inferred channel **bindings**
 - In SoS, the binding between channels must be **exogenous**
 - **Problem:** In the π -Calculus binding is endogenous
 - In SoS, the binding must be **constrained** by local contexts
 - **Problem:** In the π -Calculus binding is unconstrained
 - In SoS, the binding between channels must be **intentional**
 - **Problem:** In the π -Calculus binding is extensional
 - In SoS, the binding between channels must be **mediated**
 - **Problem:** In the π -Calculus binding is unmediated

Formal Approach for Describing SoS Architectures: The π -Calculus for SoS

- Design decisions for the π -Calculus for SoS
 - Generalization of the π -Calculus with mediated constraints
 - Subsuming the original π -Calculus
 - Coping with uncertainty
 - In SoS, partial information contributes to uncertainty, in addition to the uncertainty of emergent behavior
 - Definition of an enhanced π -Calculus based on
 - **Concurrent interacting processes**
 - **Concurrent constraints** on interactions
 - **Inferred bindings** from concurrent processes and constraints: **exogenous, constrained, intentional, mediated**
 - Emergent behavior
 - Drawn from constrained interactions



π -Calculus for SoS

Formal Approach for Describing SoS Architectures: The π -Calculus for SoS

- **The π -Calculus for SoS**: meeting the needs of SoS architecture description
 - the π -Calculus for SoS generalizes the π -Calculus with the notion of computing with partial information based on concurrent constraints
 - A **constraint** represents partial information on the state of the environment as perceived by mediated constituent systems
 - During the computation, the current state of the environment is specified by a set of told constraints
 - Processes can change the state of the environment by telling information
 - **tell** new constraints or **untell** existing constraints
 - Processes can synchronize by entailing information from the environment
 - **ask** whether a given constraint can be inferred from the told constraints in the environment

Abstract Syntax of the π -Calculus for SoS

- The formal definition of the π -Calculus for SoS encompasses its formal abstract syntax and formal semantics
- formal operational semantics of π -Calculus for SoS is defined by means of a formal transition system, expressed by labelled transition rules

Transition rule:
$$\frac{P_1 \xrightarrow{\alpha_1} P_1' \dots P_n \xrightarrow{\alpha_n} P_n'}{C \xrightarrow{\alpha} C'}$$

where side conditions

Abstract syntax of π -Calculus for SoS

```

constrainedBehavior ::= behavior1
| restriction1 . constrainedBehavior1           – Constrained Behavior
| behavior name1 ( value0 ..., valuen ) is { behavior1 } – Definition
| constraint name1 is { constraint1 }           – Constraint Definition
| compose { constrainedBehavior0 ... and constrainedBehaviorn }

behavior ::= baseBehavior1
| restriction1 . behavior1                       – Unconstrained Behavior
| repeat { behavior1 }                          – Repeat
| apply name1 ( value0 ..., valuen )          – Application
| compose { behavior0 ... and behaviorn }      – Composition

baseBehavior ::= action1 . behavior1             – Sequence
| choose { action0 . baseBehavior0
  or action1 . baseBehavior1 ... or actionn . baseBehaviorn } – Choice
| if constraint1 then { baseBehavior1 } else { baseBehavior2 }
| done                                           – Termination

action ::= baseAction1
| tell constraint1                               – Tell
| untell constraint1                             – Unsaid
| check constraint1                             – Check
| ask constraint1                               – Ask

baseAction ::= via connection1 send value0 – Output
| via connection1 receive name0 : type0 – Input
| unobservable                                   – Unobservable

connection ::= connection name1
restriction ::= value name1 = value0 | connection1
    
```

Formal Semantics of Actions in the π -Calculus for SoS

Actions:

- **send** value via connection
- **receive** value via connection
- **unobservable** internal actions
- **tell** constraint to local environment
- **untell** constraint from local environment
- **check** if constraint is consistent with local environment
- **ask** if constraint can be entailed from local environment

Formal semantics of π -Calculus for SoS: labeled transition rules for actions

Output:

$$\text{compose} \left\{ \begin{array}{l} \text{constraint}_{0..n} \\ \text{and (via connection}_1 \text{ send value}_1 \text{ . behavior}_1) \end{array} \right\} \xrightarrow{\text{via connection}_1 \text{ send value}_1} \text{compose} \left\{ \text{constraint}_{0..n} \text{ and behavior}_1 \right\}$$

Input:

$$\text{compose} \left\{ \begin{array}{l} \text{constraint}_{0..n} \\ \text{and (via connection}_1 \text{ receive value}_1 \text{ . behavior}_1) \end{array} \right\} \xrightarrow{\text{via connection}_1 \text{ receive value}_1} \text{compose} \left\{ \begin{array}{l} \text{constraint}_{0..n} \\ \text{and (value = value}_1) \\ \text{and behavior}_1 \end{array} \right\}$$

where $(\text{constraint}_{0..n} \text{ and (value = value}_1))$ is consistent, i.e. binding (value = value_1) can be consistently asserted together with $\text{constraint}_{0..n}$

Unobservable:

$$\text{compose} \left\{ \text{constraint}_{0..n} \text{ and (unobservable . behavior}_1) \right\} \xrightarrow{\tau} \text{compose} \left\{ \text{constraint}_{0..n} \text{ and behavior}_1 \right\}$$

Tell:

$$\text{compose} \left\{ \text{constraint}_{0..m} \text{ and (tell constraint}_n \text{ . behavior}_1) \right\} \xrightarrow{\tau} \text{compose} \left\{ \text{constraint}_{0..m} \text{ and constraint}_n \text{ and behavior}_1 \right\}$$

where $(\text{constraint}_{0..m} \text{ and constraint}_n)$ is consistent, i.e. constraint_n can be consistently asserted with $\text{constraint}_{0..m}$

Untell:

$$\text{compose} \left\{ \text{constraint}_{0..n} \text{ and (untell constraint}_m \text{ . behavior}_1) \right\} \xrightarrow{\tau} \text{compose} \left\{ (\text{constraint}_{0..n} - \text{constraint}_m) \text{ and behavior}_1 \right\}$$

where $(\text{constraint}_{0..n} - \text{constraint}_m)$ is consistent, i.e. constraint_m can be consistently retracted from $\text{constraint}_{0..n}$

Check:

$$\text{compose} \left\{ \text{constraint}_{0..n} \text{ and (check constraint}_m \text{ . behavior}_1) \right\} \xrightarrow{\tau} \text{compose} \left\{ \text{constraint}_{0..n} \text{ and behavior}_1 \right\}$$

where $(\text{constraint}_{0..n} \text{ and constraint}_m)$ is consistent, i.e. constraint_m is checked to be consistent with $\text{constraint}_{0..n}$

$$\text{Ask: } \text{compose} \left\{ \text{constraint}_{0..m} \text{ and (ask constraint}_n \text{ . behavior}_1) \right\} \xrightarrow{\tau} \text{compose} \left\{ \text{constraint}_{0..m} \text{ and behavior}_1 \right\}$$

where $\text{constraint}_{0..m} \vdash \text{constraint}_n$, i.e. constraint_n can be derived from $\text{constraint}_{0..m}$

Formal Semantics of Behaviors in π -Calculus for SoS

Behaviors:

- restriction of value to local behavior
- communication of value via connection between behaviors
 - synchronization between **send** and **receive**
 - equality constraint
- extrusion of value to another behavior (open restriction & close communication)
- nondeterministic choice among behaviors
- conditional choice between behaviors
- repetition of behavior
- composition of concurrent behaviors

Formal semantics of π -Calculus for SoS: labeled transition rules for behaviors

Restriction:

$$\frac{\text{constrainedBehavior}_1 \xrightarrow{\text{action}_1} \text{constrainedBehavior}'_1}{\text{value } \text{value}_1 . \text{constrainedBehavior}_1 \xrightarrow{\text{action}_1} \text{value } \text{value}_1 . \text{constrainedBehavior}'_1}$$

where $\text{value}_1 \notin \text{names}(\text{action}_1)$, i.e. value_1 is not among the names used in action_1

Communication:

$$\frac{\text{behavior}_1 \xrightarrow{\text{via } \text{connection}_1 \text{ send } \text{value}_1} \text{behavior}'_1 \quad \text{behavior}_2 \xrightarrow{\text{via } \text{connection}_2 \text{ receive } \text{value}} \text{behavior}'_2}{\text{compose} \left\{ \begin{array}{l} \text{constraint}_{0..n} \\ \text{and } (\text{connection}_1 = \text{connection}_2) \\ \text{and } \text{behavior}_1 \text{ and } \text{behavior}_2 \end{array} \right\} \xrightarrow{\tau} \text{compose} \left\{ \begin{array}{l} \text{constraint}_{0..n} \\ \text{and } (\text{connection}_1 = \text{connection}_2) \\ \text{and } (\text{value} = \text{value}_1) \text{ and } \text{behavior}'_1 \text{ and } \text{behavior}'_2 \end{array} \right\}}$$

where $\text{connection}_1 = \text{connection}_2$, i.e. $(\text{connection}_1 = \text{connection}_2)$ is a binding resulting from an extrusion or unification

Restriction-Open:

$$\frac{\text{constrainedBehavior}_1 \xrightarrow{\text{via } \text{connection}_1 \text{ send } \text{value}_1} \text{constrainedBehavior}'_1}{\text{value } \text{value}_1 . \text{constrainedBehavior}_1 \xrightarrow{\text{via } \text{connection}_1 \text{ send } \text{value}_1} \text{constrainedBehavior}'_1}$$

where $\text{value}_1 \neq \text{connection}_1$, i.e. value_1 cannot be used for connection as it is restricted

Communication-Close:

$$\frac{\text{behavior}_1 \xrightarrow{\text{value } \text{connection} . \text{via } \text{connection}_1 \text{ send } \text{connection}} \text{behavior}'_1 \quad \text{behavior}_2 \xrightarrow{\text{via } \text{connection}_2 \text{ receive } \text{value}} \text{behavior}'_2}{\text{compose} \left\{ \begin{array}{l} \text{constraint}_{0..n} \\ \text{and } (\text{connection}_1 = \text{connection}_2) \\ \text{and } \text{behavior}_1 \text{ and } \text{behavior}_2 \end{array} \right\} \xrightarrow{\tau} \text{value } \text{connection} . \text{compose} \left\{ \begin{array}{l} \text{constraint}_{0..n} \\ \text{and } (\text{connection}_1 = \text{connection}_2) \\ \text{and } (\text{value} = \text{connection}) \\ \text{and } \text{behavior}'_1 \text{ and } \text{behavior}'_2 \end{array} \right\}}$$

where $\text{value} \notin \text{free}(\text{behavior}_2)$, i.e. value is not restricted in behavior_2 while connection is restricted in behavior_1

Choice:

$$\frac{\text{constraint}_{0..n} \text{ and } (\text{action}_i . \text{behavior}'_i) \xrightarrow{\text{action}_i} \text{constraint}_{0..n}' \text{ and } \text{behavior}'_i}{\text{compose} \left\{ \begin{array}{l} \text{constraint}_{0..n} \\ \text{and } \text{choose} \left\{ \begin{array}{l} \text{action}_0 . \text{behavior}'_0 \dots \text{or } \text{action}_m . \text{behavior}'_m \end{array} \right\} \end{array} \right\} \xrightarrow{\text{action}_i} \text{compose} \left\{ \begin{array}{l} \text{constraint}_{0..n}' \\ \text{and } \text{behavior}'_i \end{array} \right\}}$$

where $i \in 0..m$, i.e. only one of the actions $\text{action}_{0..m}$ is performed

Conditional-Then:

$$\frac{\text{behavior}_1 \xrightarrow{\text{action}_1} \text{behavior}'_1 \quad \text{constraint} = \text{true}}{\text{compose} \left\{ \text{constraint}_{0..n} \text{ and } (\text{if } \text{constraint} \text{ then } \text{behavior}_1 \text{ else } \text{behavior}_2) \right\} \xrightarrow{\text{action}_1} \text{compose} \left\{ \text{constraint}_{0..n} \text{ and } \text{behavior}'_1 \right\}}$$

Conditional-Else:

$$\frac{\text{behavior}_2 \xrightarrow{\text{action}_2} \text{behavior}'_2 \quad \text{constraint} = \text{false}}{\text{compose} \left\{ \text{constraint}_{0..n} \text{ and } (\text{if } \text{constraint} \text{ then } \text{behavior}_1 \text{ else } \text{behavior}_2) \right\} \xrightarrow{\text{action}_1} \text{compose} \left\{ \text{constraint}_{0..n} \text{ and } \text{behavior}'_2 \right\}}$$

Repetition:

$$\frac{\text{behavior}_1 \xrightarrow{\text{action}_1} \text{behavior}'_1}{\text{repeat} \left\{ \text{behavior}_1 \right\} \xrightarrow{\text{action}_1} \text{behavior}'_1 . \text{repeat} \left\{ \text{behavior}_1 \right\}}$$

where $\text{behavior}'_1 . \text{behavior}_1$ is a sequential composition, i.e. $\text{behavior}'_1$ must be performed before behavior_1

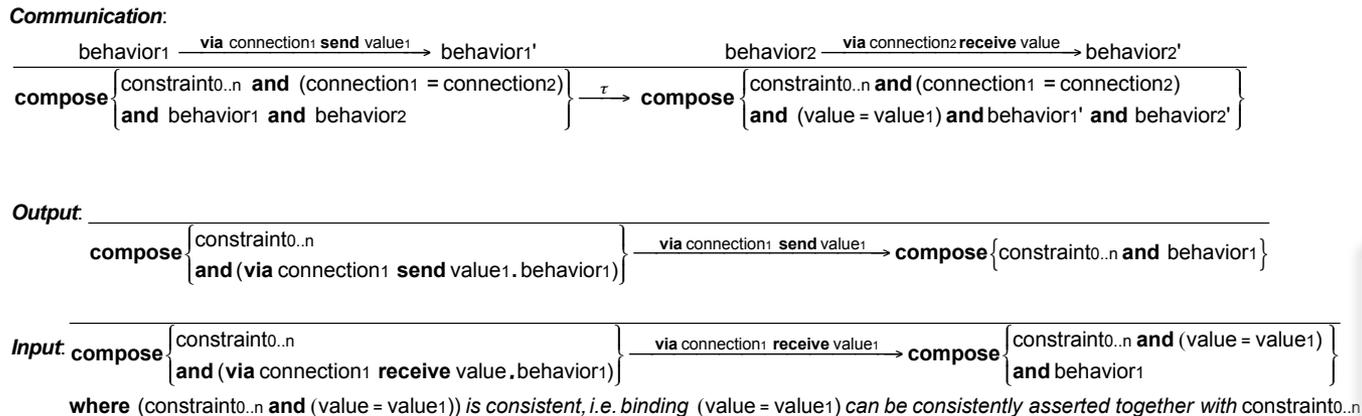
Composition:

$$\frac{\text{constrainedBehavior}_i \xrightarrow{\text{action}_i} \text{constrainedBehavior}'_i}{\text{compose} \left\{ \begin{array}{l} \text{constrainedBehavior}_0 \dots \\ \text{and } \text{constrainedBehavior}_i \\ \text{and } \text{constrainedBehavior}_n \end{array} \right\} \xrightarrow{\text{action}_i} \text{compose} \left\{ \begin{array}{l} \text{constrainedBehavior}_0 \dots \\ \text{and } \text{constrainedBehavior}'_i \\ \text{and } \text{constrainedBehavior}_n \end{array} \right\}}$$

where $i \in 1..n$ and $\text{bound}(\text{action}_i) \cap \text{free}(\text{constrainedBehavior}_{0..n-i}) = \emptyset$, i.e. restricted names in action_i are not restricted elsewhere

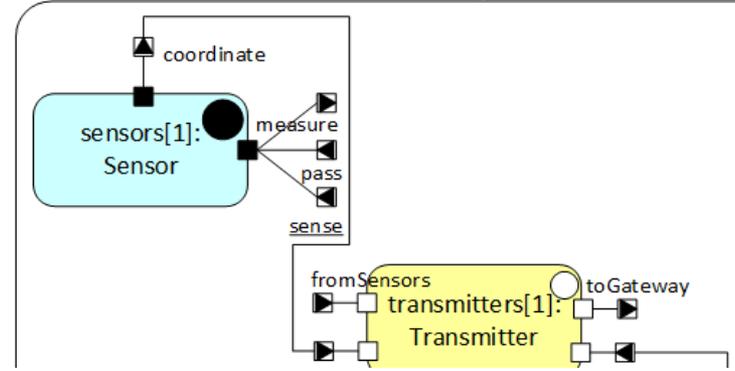
Understanding the Semantics of the π -Calculus for SoS

Communication



```
Sensors[1] : system Sensor(lps=Coordinate::(10,10)) is { ...
  behavior sensing is {
    value sensorcoordinate is Coordinate = lps
    tell sensorlocation is {sensorcoordinate = lps}
    via location::coordinate send sensorcoordinate
    via energy::threshold receive powerthreshold
    repeat {
      via energy::power receive powerlevel
      if (powerlevel > powerthreshold) then {
        tell powering is {powerlevel > powerthreshold}
        choose{
          via measurement::sense receive data
          via measurement::measure send
            tuple{coordinate=lps,depth=data::convert()}
        } or {
          via measurement::pass receive data
          via measurement::measure send data
        }
      }
    }
  }
}
```

```
transmitters[1] : mediator
  Transmitter(distancebetweenegates:Distance) is { ...
    behavior transmitting is {
      via location::fromCoordinate receive sendercoordinate
      via location::toCoordinate receive receivercoordinate
      ask sendercoordinate::distance(receivercoordinate)
        < distancebetweenegates
      repeat {
        via transmit::fromSensors receive measure
        via transmit::towardsGateway send measure
      }
    }
  }
```

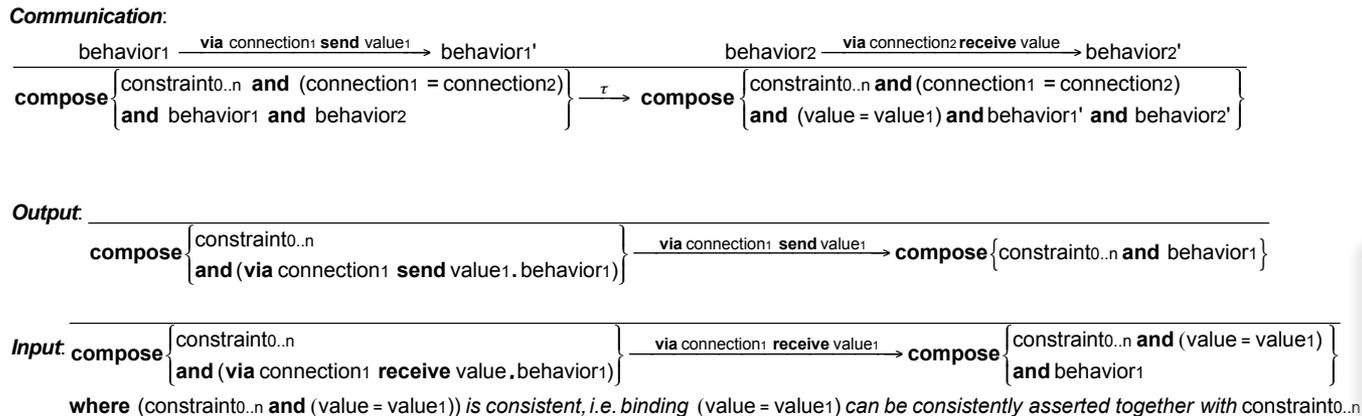


Equality from coalition

constraint {sensors[1]::location::coordinate = transmitters[1]::location::fromCoordinate}

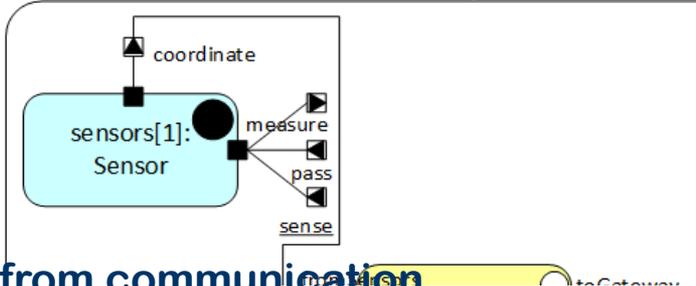
Understanding the Semantics of the π -Calculus for SoS

Communication



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  behavior sensing is {
    value sensorcoordinate is Coordinate = lps
    tell sensorlocation is {sensorcoordinate = lps}
    via location::coordinate send sensorcoordinate
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    repeat {
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      repeat {
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      }
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  }
```



Equality from communication

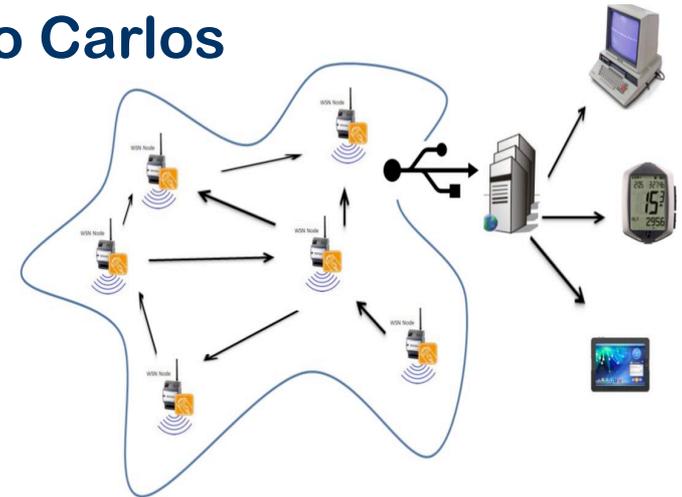
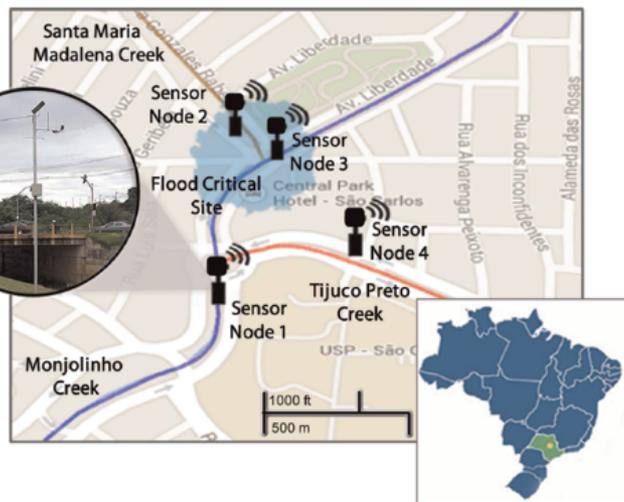
```
constraint {transmitters[1]::sendercoordinate = Coordinate::(10,10)}
```

Equality from coalition

```
constraint {sensors[1]::location::coordinate = transmitters[1]::location::fromCoordinate}
```

Validating the Formal Operational Semantics of SosADL: WSN-based Urban River Monitoring SoS

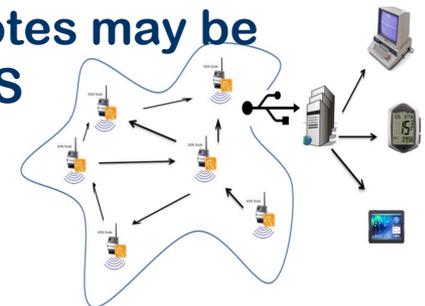
Monjolinho river crossing the city of Sao Carlos



- The Urban River Monitoring SoS is based on two kinds of constituent systems:
 - wireless river sensors (for measuring river level depth via pressure physical sensing)
 - a gateway base station (for analyzing variations of river level depths and warning on the risk of flash flood)

Applying π -Calculus for SoS: Urban River Monitoring

- Sensor motes are operated by different City Councils in the Urban area
- **Operational independence of constituent systems**
 - Each sensor mote operates in a way that is independent of other sensor motes (which may belong to different organizations and have different missions, e.g. pollution control, water supply, ...)
- **Managerial independence of constituent systems**
 - Each sensor mote has its own strategy for transmission vs. energy consumption
- **Geographical distribution of constituent systems**
 - Sensor motes are geographically distributed along the river
- **Evolutionary development of system-of-systems**
 - New sensor motes may be installed, existing sensor motes may be changed or uninstalled without any control from the SoS
- **Emergent behavior of system-of-systems**
 - Sensor motes together, with the gateway, will make emerge the behavior of flood detection

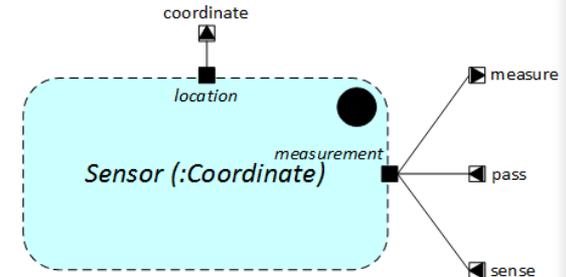


Illustrating the Formal Operational Semantics of SosADL: WSN-based Urban River Monitoring SoS

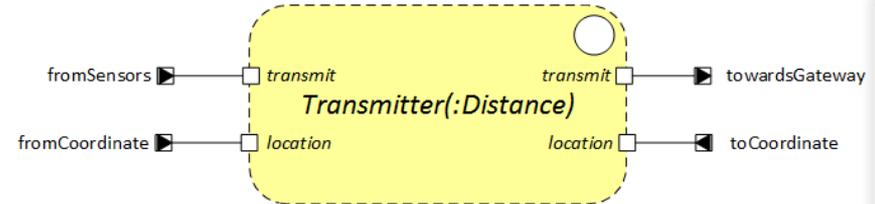
```

system Sensor(lps: Coordinate) is { ...
  behavior sensing is {
    value sensorcoordinate is Coordinate = lps
    tell sensorlocation is {sensorcoordinate = lps}
    via location::coordinate send sensorcoordinate
    via energy::threshold receive powerthreshold
    repeat {
      via energy::power receive powerlevel
      if (powerlevel > powerthreshold) then {
        tell powering is {powerlevel > powerthreshold}
        choose{
          via measurement::sense receive data
          via measurement::measure send
            tuple{coordinate=lps,depth=data::convert()}
        } or {
          via measurement::pass receive data
          via measurement::measure send data
        }
      }
    }
  }
}

```



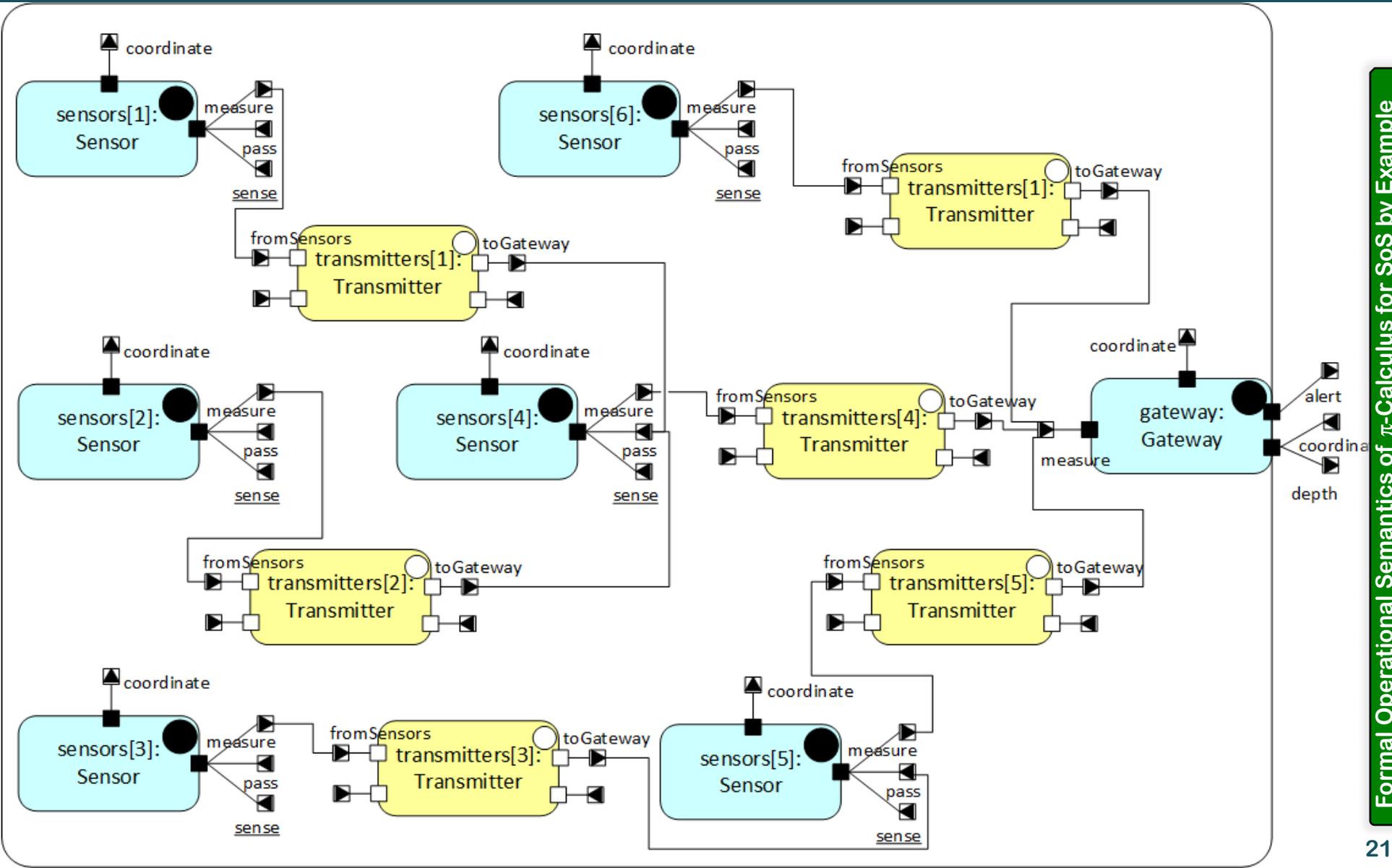
Illustrating the Formal Operational Semantics of SosADL: WSN-based Urban River Monitoring SoS



```

mediator Transmitter(distancebetweenengates:Distance) is { ...
  behavior transmitting is {
    via location::fromCoordinate receive sendercoordinate
    via location::toCoordinate receive receivercoordinate
    ask sendercoordinate::distance(receivercoordinate)
      < distancebetweenengates
    repeat {
      via transmit::fromSensors receive measure
      via transmit::towardsGateway send measure
    }
  }
}
  
```

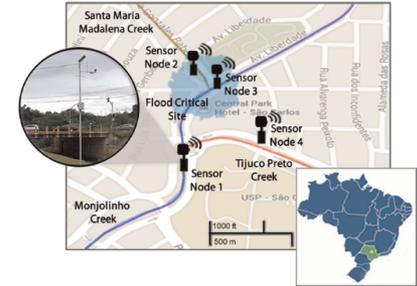
Urban River Monitoring SoS Architecture: Concretion (snapshot)



Validation through Real Application Cases

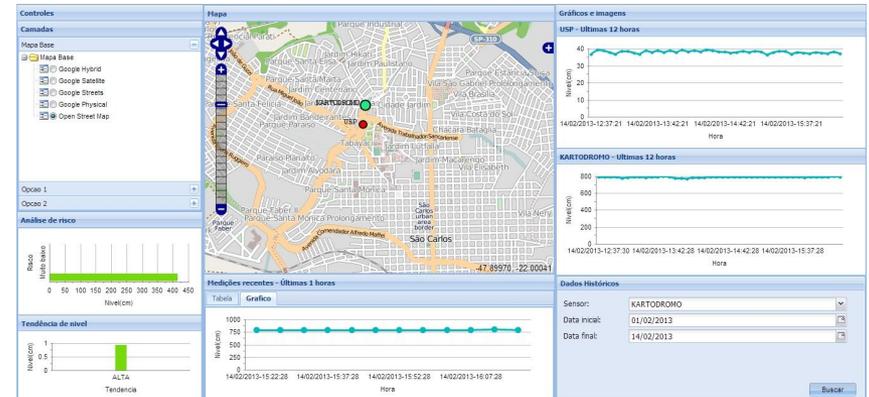
■ Urban River Monitoring SoS

- Monjolinho river crossing the city of Sao Carlos
 - XBee motes, ZigBee transmissions, Solar panels...



■ Flood Monitoring and Emergency Response SoS

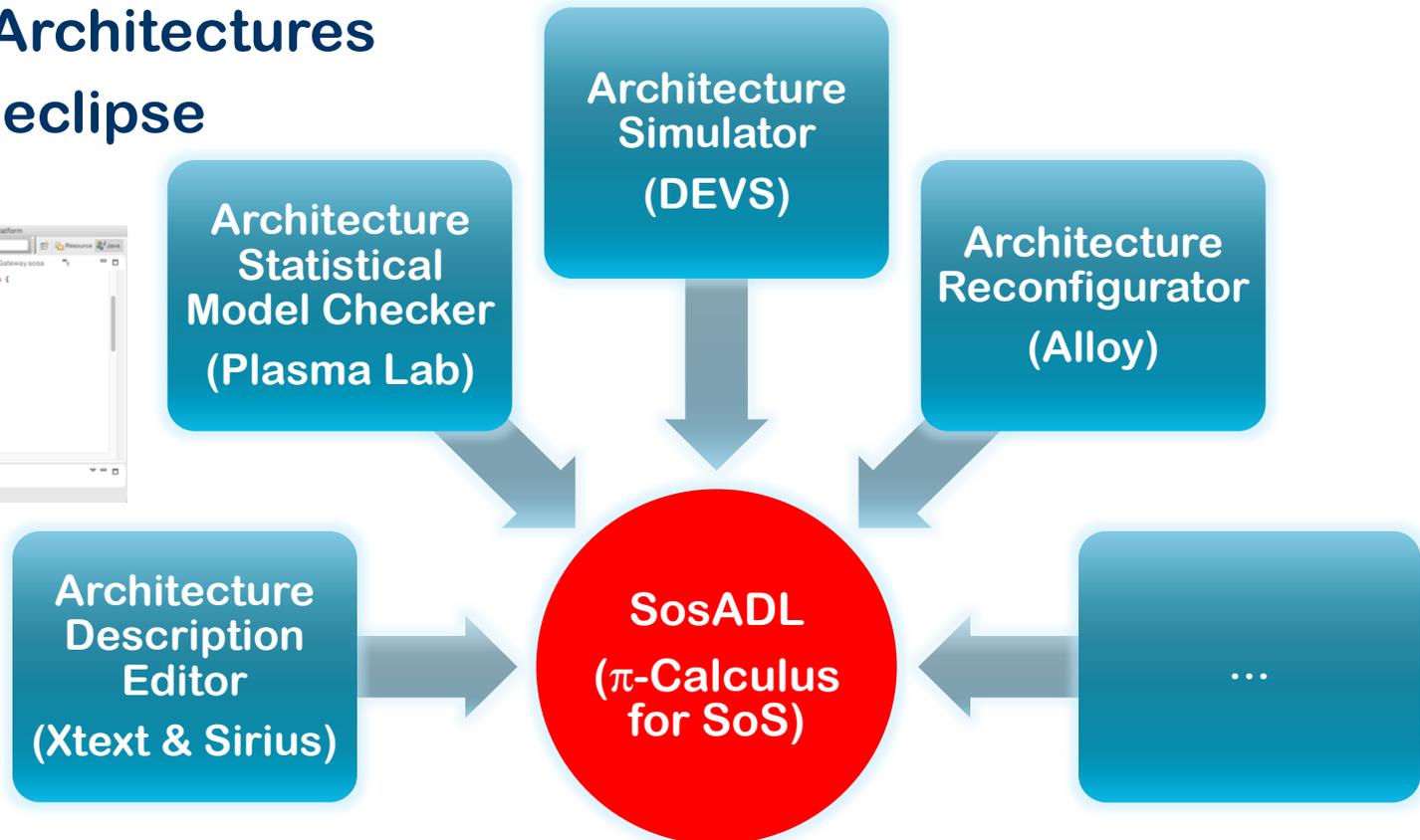
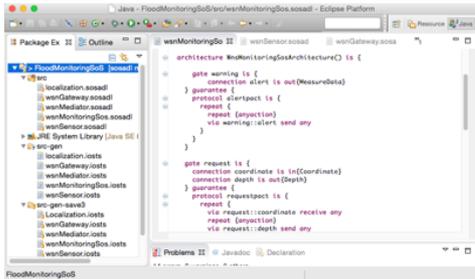
- Wireless River Sensors
- Telecommunication Gateways
- Unmanned Aerial Vehicles (UAVs)
- Vehicular Ad Hoc Networks (VANETs)
- Meteorological Centers
- Fire and Rescue Services
- Hospital Centers
- Police Departments
- Short Message Service Centers
- Social Networks



Toolset for π -Calculus for SoS

- **SosADE (SoS Architecture Development Environment)** for supporting the application of SosADL based on the **π -Calculus for SoS** for description and analysis of SoS Software Architectures

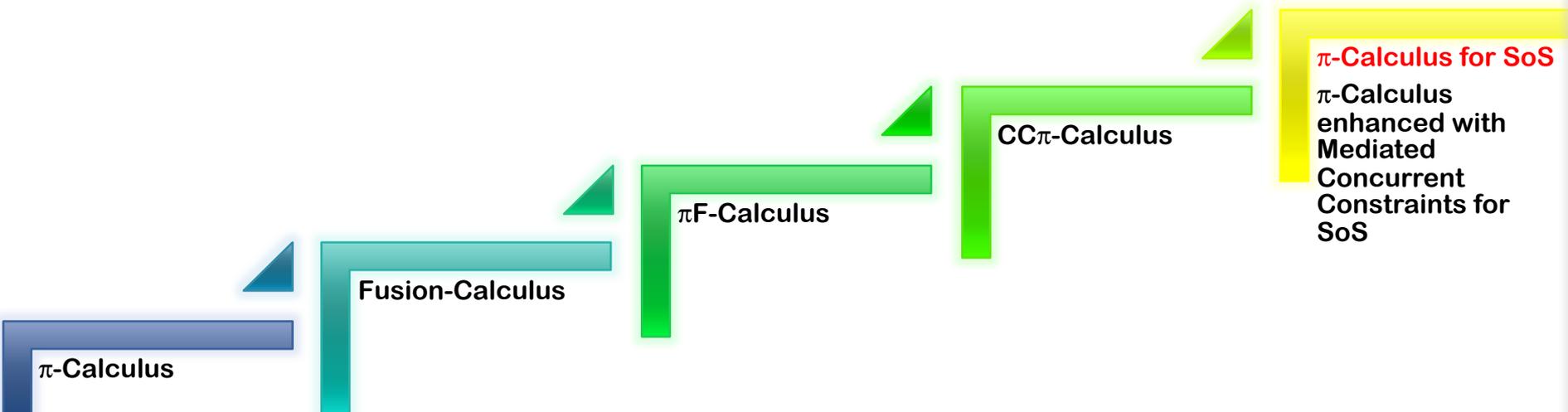
- Plugins eclipse



Conclusion: Novel π -Calculus coping with SoS needs

■ π -Calculus for SoS

- Enhances the expressiveness of the π -Calculus with Mediated Concurrent Constraints for coping with SoS characteristics
 - exogenous, intentional, constrained and mediated channel bindings subject to uncertainty
- Provides a novel π -Calculus as formal foundation for **SosADL**



Conclusion: Novel π -Calculus coping with SoS needs

- **π -Calculus for SoS** provides a formal foundation having the expressiveness to address the challenge of describing architectures of Software-intensive SoSs
 - The π -Calculus for SoS supports **automated verification of correctness properties of SoS architectures**
 - The π -Calculus for SoS supports **validation through executable specifications**
 - Including **simulation to validate and discover emergent behaviors**
- π -Calculus for SoS provided the formal foundation of a novel ADL for SoS: SosADL
- It was applied for architecting a Flood Monitoring and Emergency Response SoS in the Monjolinho river crossing the City of Sao Carlos
- Several new applications are on the way with DCNS, IBM, ICMC, SEGULA... for formal modeling SoS Architectures

Thank You

Questions?

The π -Calculus for SoS: Novel π -Calculus for the Formal Modeling of Software-intensive Systems-of-Systems

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